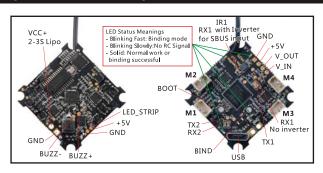


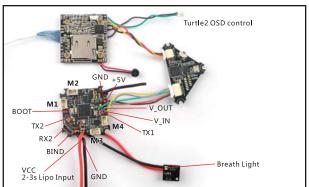
Specifications	
Brand Name: Happymodel	
Item Name: Mobula7 HD 2-3S 75mm Brushless whoop drone	
Wheelbase: 75mm	
Size: 98mm*98mm*45mm	
Weight: 72g(with Original 3s 300mah Lipo battery)	

Package includes:

Item Name	Qty		
Mobula7 V3 Frame	1		
Option1: Crazybee F4FR V2.0 PRO FC built-in Frsky NON-EU RX			
Option2: Crazybee F4FS V2.0 PRO FC built-in Flysky RX	1		
Option3: Crazybee F4DX V2.0 PRO FC built-in Serial-bus DSM2/X RX	1		
Option4: Crazybee F4 V2.0 PRO FC no RX verion			
EX1102 KV10000 Motor	4		
40mm propeller(4cw+4ccw)	1		
Caddx Turtle v2+1080p 60fps DVR	1		
Whoop_vtx 5.8G 40ch 25mw-200mw VTX	1		
3S 11.4v 300mah 30C/60C battery	1		
Propeller disassemble tool	1		
Screwdriver	1		

Flight controller connection diagram

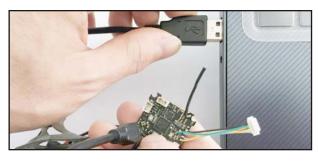




Binding procedure

Binding. .

1. Press and hold the bind button and then Plug the USB to power for the Crazybee F4 PRO FS flight controller, the LED Combo(2 red LED an 2 white LED) will blinking fast, this indicate the Crazybee F4 PRO FS flight controller is in binding mode and then release the binding button



 $Another \,easy\,way\,to\,getting\,into\,binding\,mode (Need\,update\,firmware\,to\,betaflight_4.0.0_CRAZYBEEF4FS-RC2.hex):$

Plug usb and go to the CLI command in the Betaflight configurator ,then type "bind_rx_spi", the Crazybee F4FS Pro flight controller will getting into binding mode , and then you just make the Flysky transmitter to Binding with it.

\$M>-107V₇₁□-\$M>7t_{Tr}ARM; ANGLE; HORIZON; HEADFREE; FAILSAFE; ANTI 6
MIX; CAMERA CONTROL 1; CAMERA CONTROL 2; CAMERA CONTROL 3; FLIP 0
CONTROL; —\$M>4-, □□□!□₁□□□□□+□¹□□⁴,□□□
Entering CLI Mode, type 'exit' to return, or 'help'
bind_rx_spi

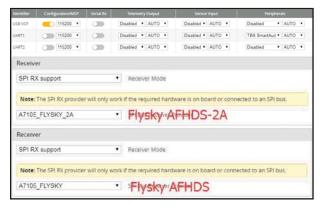
Mobula 7 HD brushless whoop Racing Drone Flysky version

2.Turn on your Flysky transmitter, and Choose receiver mode AFHDS-2A or AFHDS according to your Betaflight receiver configuration(A7105_Flysky_2A=AFHDS-2A, A7105_Flysky=AFHDS) 3.ENT RX [BIND] to binding with the Crazybee F4 POR Flight controller, the LED Combo(2 red LED and 2 white LED) will getting to be solid on the flight controller, this indicate binding successfully, the AFHDS-2A radio will auto exist the binding mode but the AFHDS radio should exist binding mode by yourself.



Receiver configuration

Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select A7105_Flysky_2A Provider for AFHDS-2A Protocol Radio transmitter or Select A7105_Flysky Provider for AFHDS Protocol Radio transmitter, don't enable Serial RX since the Crazybee F4 PRO Flight controller is integrated SPI BUS Receiver



Arm/Disarm the Motor

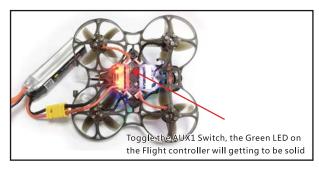
1. The Default Arm/Disarm switch for Mobula 7 HD is AUX1 (Channel 5), and you can also customize it with Betaflight Configurator.



2. Set Arm/Disarm switch for your Flysky Radio: Move to the Aux.channels interface, Set "SWA" or "SWB" or "SWC" switch etc. for Ch5 to ARM/DISARM the motor.

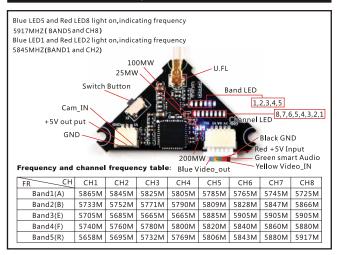


3.The default channel map for Mobula7 HD Flysky version is AETR1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch ,the Green LED on the flight controller will getting to be solid, this indicates the motor was armed . And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Mobula7 HD level before arming .Be careful and enjoy your flight now!





VTX Bands and Channels setup



There are 3 ways to switch the vtx channels:

1.Long press the switch button to change the Band of the VTX, shorter press the switch button to change the channels of the VTX.

(Can't save ,it will lost the channel while re-power for the Mobula 7 HD since the Smartaudio funciton enalbed)

2. Go to Betaflight CLI, type the command:

Set vtx_band=3

Set vtx_channel=1

Set vtx_freq=5705

save

Notes: The vtx_freq should match the vtx_band and vtx_channle as the VTX Channel list shows. For example, if you set vtx_freq=5732, you should set vtx_band=5 and vtx_channel=3

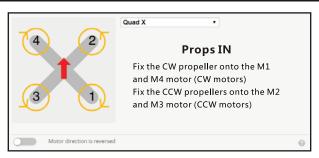
3. Enable Smartaudio for UART1, then move the stick of the transmitter (THR MID+YAW LEFT

+ PITCH UP) to enter OSD Menu, Enter to Features, then enter to VTX SA to set VTX Band and channel

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals			
USB VCP	115200 +		Disabled • AUTO •	Disabled • AUTO •	Disabled ▼ AUTO ▼			
UART1	115200 •		Disabled ▼ AUTO ▼	Disabled • AUTO •	TBS SmartAud ▼ AUTO ▼			
UART2	115200 🔻		Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼			



Mixer type and ESC/motor protocol





Default PID setting

	Propor	tior	untegra		Derivat	ive	Feedfo	rwa	rdRC Rate		Super Rate	Max Vel [deg/s]	RC Expo
Basic/Acr	0												6
ROLL	50	\$	45	\$	27	\$	60	\$	7.00	÷	0.75	\$ 800	0.23 3
PITCH	50	\$	50	:	30	:	60	\$	5		0.75	\$ 800	1
YAW	72	\$	55	\$	0	\$	100	\$	1.00	\$	0.70	\$ 667	0.00 \$

ESC Check and Flash firmware

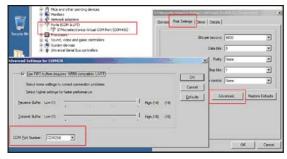
1.Download New release Blhelisuite from:

https://www.mediafire.com/folder/dx6kfaasyo24l/BLHeliSuite

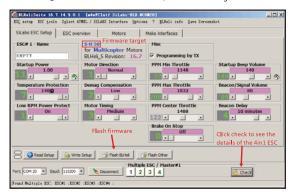
2.Connect the Crazybee F4 PRO flight controller to computer and power for it with battery



3.Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step:



4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHEILISUITE, the firmware Target is "S-H-50"



Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

2.Install STM BOOTLOAD Driver (STM Device in DFU MODE)
3.Open Betaflight configurator and choose firmware target "CrazybeeF4F5" ,then select the firmware version.

4.There are 2 ways to get in DFU Mode: 1). solder the boot pad and then plug USB to computer 2). loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically.

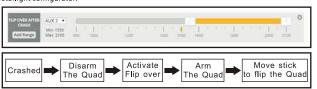
5.Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.

6.Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.



"Flip over after crash" procedure

Set one channel of your radio transmitter to activate the Flip over function in the Mode tab of Betaflight configurator.



Notes:

- 1. Add external Sbus RX, Disable SPI RX---Connect SBUS wire to the IRX1 pad ---Enable Serial RX for UART1---Choose serial_based receiver and Sbus protocol
- 2. Add external Crossfire rx , use TX2 RX2 port
- 3. Breath light meanings: If the single cell voltage > 3.6v , the LED turn to green color, if the single cell voltage < 3.3v the LED turn to red color .
- 4. No videos from Caddx turtle2 if just power from USB , need to connect the battery