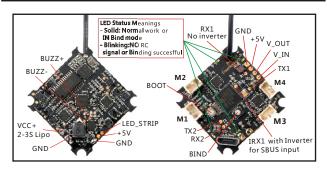


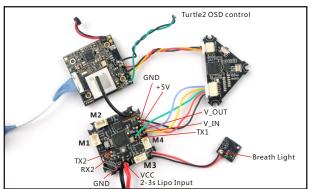
Specifications	
Brand Name: Happymodel	•
Item Name: Mobula7 HD 2-3S 75mm Brushless whoop drone	
Wheelbase: 75mm	
Size: 98mm*98mm*45mm	
Weight: 72g(with Original 3s 300mah Lipo battery )	

## Package includes:

Item Name	Qty
Mobula7 V3 Frame	1
Option1: Crazybee F4FR V2.0 PRO FC built-in Frsky NON-EU RX	
Option2: Crazybee F4FS V2.0 PRO FC built-in Flysky RX	1
Option3: Crazybee F4DX V2.0 PRO FC built-in Serial-bus DSM2/X RX	]
Option4: Crazybee F4 V2.0 PRO FC no RX verion	
EX1102 KV10000 Motor	4
40mm propeller(4cw+4ccw)	1
Caddx Turtle v2+1080p 60fps DVR	1
Whoop_vtx 5.8G 40ch 25mw-200mw VTX	1
3S 11.4v 300mah 30C/60C battery	1
Propeller disassemble tool	1
Screwdriver	1

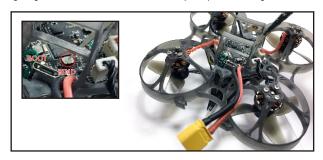
#### Flight controller connection diagram





## Binding procedure

1.Power for the Mobula7 HD and the LED Combo(2 red LED and 2 white LED) will blinking slowly, then Press and hold the bind button for 2 seconds, the LED Combo(2 red led and 2 white led) will getting to be solid, this indicate the Mobula7 HD Quadcopter is in binding mode



Another easy way to binding with the Frsky transmitter Plug usb and go to the CLI command in the Betaflight configurator, then type "bind", the Crazybee F4FR flight controller will getting into binding mode, and then you just make the Frsky transmitter to Bind mode.

2. Turn on your Frsky Taranis transmitter, and move to BIND OPTION from SETUP MENU, Choose receiver mode D16 or D8 according to your Betaflight receiver configuration (Frsky\_X = D16 mode, Frsky\_D=D8 mode)



3.ENT [Bind] to binding with the Mobula7 HD, the LED Combo(2 red led and 2 white led) will blinking slowly on the flight controller, this indicate binding successfully, and then exist binding mode of your Frsky transmitter, the LED Combo(2 red led and 2 white led) will getting to be solid again, this indicate working normal.

## Receiver configuration

Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select FRSKY\_X Provider for FRSKY D16 MODE or Select FRSKY\_D Provider for FRSKY D8 MODE, don't enable Serial RX since the CRAZYBEE Flight controller is integrated SPI BUS Receiver



#### Arm/Disarm the Motor

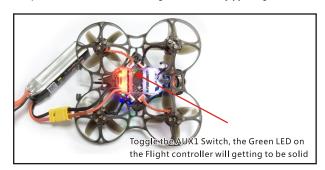
 $1. The \ Default\ Arm/Disarm\ switch for\ Mobula 7\ HD\ is\ AUX1 (Channel\ 5), and\ you\ can also \ customize\ it\ with\ Betaflight\ Configurator.$ 



2.Turn on the Frsky transmitter (Use X9D+ as an example) and move to the MIXER interface, Set "SA" or "SB" switch etc. for Ch5 to ARM/DISARM the motor.

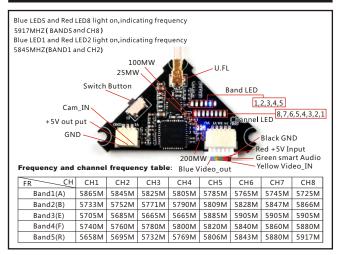


3.The default channel map for Mobula7 HD Frsky version is TAER1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch ,the Green LED on the flight controller will getting to be solid, this indicates the motor was armed And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Mobula7 HD level before arming. Be careful and enjoy your flight now!





#### VTX Bands and Channels setup



There are 3 ways to switch the vtx channels:

1.Long press the switch button to change the Band of the VTX, shorter press the switch button to change the channels of the VTX.

(Can't save ,it will lost the channel while re-power for the Mobula 7 HD since the Smartaudio funciton enalbed)

2. Go to Betaflight CLI, type the command:

Set vtx\_band=3

Set vtx\_channel=1

Set vtx\_freq=5705

save

Notes: The vtx\_freq should match the vtx\_band and vtx\_channle as the VTX Channel list shows. For example, if you set vtx\_freq=5732, you should set vtx\_band=5 and vtx\_channel=3

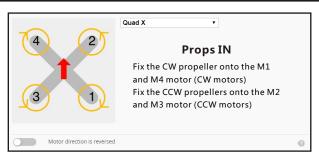
3. Enable Smartaudio for UART1, then move the stick of the transmitter (THR MID+YAW LEFT

+ PITCH UP) to enter OSD Menu, Enter to Features, then enter to VTX SA to set VTX Band and channel

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals			
USB VCP	115200 🔻		Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼			
UART1	115200 🔻		Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼	TBS SmartAud ▼ AUTO ▼			
UART2	115200 🔻		Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼	Disabled ▼ AUTO ▼			



## Mixer type and ESC/motor protocol





## Default PID setting

	Propor	tion	alntegra	ı	Derivat	ive	Feedfo	rwa	rdRC Rate	Super Rate	ı	Max Vel [deg/s]	RC Expo
Basic/Acro													0
ROLL	50	\$	45	\$	27	\$	60	\$	1.00 \$	0.75	\$	800	0.23 🛊
PITCH	50	\$	50	\$	30	\$	60	\$	)	0.75	\$	800	)
YAW	72	\$	55	\$	0	\$	100	\$	1.00 \$	0.70	\$	667	0.00 \$

## ESC Check and Flash firmware

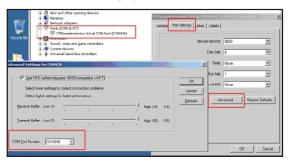
1.Download New release Blhelisuite from:

https://www.mediafire.com/folder/dx6kfaasyo24l/BLHeliSuite

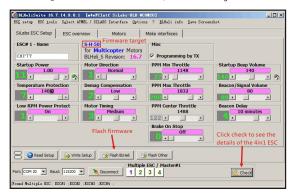
2. Connect the Crazybee F4 PRO flight controller to computer and power for it with battery



3.Open the Device Manager of your computer, find the Ports, please make sure the Comport Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step:



4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli\_s firmware via the BLHEILISUITE, the firmware Target is "S-H-50"



## Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

2.Install STM BOOTLOAD Driver (STM Device in DFU MODE)

3.Open Betaflight configurator and choose firmware target "CrazybeeF4FR" ,then select the firmware version.

4.There are 2 ways to get in DFU Mode: 1). solder the boot pad and then plug USB to computer 2). loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically.

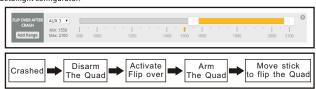
5.Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.

6.Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.



# "Flip over after crash" procedure

Set one channel of your radio transmitter to activate the Flip over function in the Mode tab of Betaflight configurator.



#### Notes:

- $1.\,Add\,external\,Sbus\,RX,\,Disable\,SPI\,RX---Connect\,SBUS\,wire\,to\,the\,IRX1\,pad\,---Enable\,Serial\,RX\,for\,UART1---Choose\,serial\_based\,receiver\,and\,Sbus\,protocol$
- 2. Add external Crossfire rx , use TX2 RX2 port
- 3. Breath light meanings: If the single cell voltage > 3.6v , the LED turn to green color, if the single cell voltage < 3.3v the LED turn to red color .
- 4. No videos from Caddx turtle2 if just power from USB , need to connect the battery