

Features

Toothpick HD and Whoop HD 2 in 1 combo (Default Comes in Toothpick HD style)

Toothpick style compatible both 2.5inch or 3inch propellers

New design EX1203 High efficiency brushless motors Caddx baby Turtle provide 1080P 60FPS DVR video

Caucas Anala adicatable

Camera Angle adjustable

Full range receiver options
Buzzer ready

Smooth and powerful

Compatible both for 2s-3s Lipo/LIHV

Specifications

Brand Name: Happymodel

Item Name: Larva-X HD Micro FPV brushless Drone Wheelbase: 125mm

Size: 105mm*105mm*35mm(without propellers)

Weight: Toothpick style ductless 63g (without battery)

Whoop style ducted 79g (without battery)

Receiver options:

Frsky SPI receiver

Flysky SPI receiver

DSM2/DSMX compatible receiver

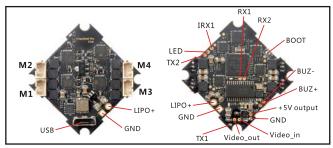
Frsky XM+ receiver

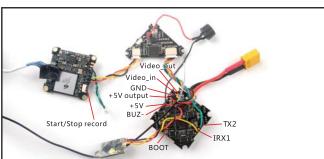
Frsky R-XSR receiver

TBS Nano CRSF receiver

Package includes	
Item Name	Qty
Larva-X HD frame (with Toothpick style canopy and Whoop style canopy)	1
Whoop duct for Larva-X HD	4
SPI Receiver Option1: Crazybee F4FR V3.0 PRO FC built-in Frsky SPI D8 RX	
SPI Receiver Option2: Crazybee F4FS V3.0 PRO FC built-in Flysky SPI RX	
Receiver Option3: Crazybee F4 V3.0 PRO FC with external DSM2/DSMX RX	1
Receiver Option4: Crazybee F4 V3.0 PRO FC with external Frsky XM+ receiver	
Receiver Option5: Crazybee F4 V3.0 PRO FC with external Frsky RXSR receiver	
Receiver Option6: Crazybee F4 V3.0 PRO FC with external TBS Crossfire Nano RX	
EX1203 KV6200 brushless motors	4
Propeller sets	1
CADDX Baby turtle	1
VTX 5.8g 25mw~200mw switchable	1
3S 11.1v 450mah 75c Li-po battery	2
5.8g Micro UXII antenna	1
Propeller disassemble tool	1

Flight controller connection diagram





Binding procedure

*Notes

The RXSR is coming with Accst firmware, if your transmitter is access version, please change firmware.

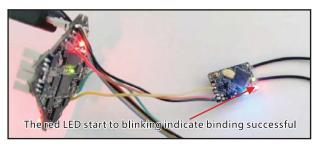
1. Press and hold the bind button then plug the USB, the Blue , Red and Green LED will getting to be solid , this indicate the RXSR receiver is in bind mode .



 $2. Then \, Turn \, on \, your \, Frsky \, transmitter \, and \, move \, to \, bind \, option \, from \, SETUP \, MENU, \, choose \, receiver \, mode \, \, ``D16"$



3.ENT [bind] to binding with the RXSR receiver, then the red LED on the RXSR receiver starting to blinking slowly, this indicates the bind is successfully. Exit the bind mode for the transmitter and repower for the RXSR receiver. Then the green and blue LED getting to solid, this indicates the receiver and the transmitter works normal



Receiver configuration

1. Soldering the SBUS_OUT pad of the RXSR receiver to IRX1 pad of the Crazybee F4 PRO V3.0 Flight controller . Enable Serial RX for UART1

Identifier USB VCF	Configuration/MSP	Sessifix	Telemetry Output	Sensor Input	Periphinals			
	115200 •		Disabled • AUTO •	Disabled • AUTO •	Disabled • AUTO •			
UARTI	115200 •	CO	Disabled • AUTO •	Disabled • AUTO •	Disabled • AUTO •			
UART2	115200 •		Disabled + AUTO +	Disabled • AUTO •	VTX (TBS Smv + AUTO +			

2. Select Serial-based receiver for the receiver mode and SBUS for the Serial Receiver provider



 $3. If you want to set RSSI to Betaflight osd , please check these articles https://oscarliang.com/rssi-ppm-channel-taranis/https://www.youtube.com/watch?v=fGX_ka2pqps$

Arm/Disarm the Motor

1. The Default Arm/Disarm switch for Larva X HD is AUX1(Channel 5), and you can also customize it with Betaflight Configurator.



2. Turn on the Frsky transmitter (Use X9D+ as an example) and move to the MIXER interface, Set "SA" or "SB" switch etc. for Ch5 to ARM/DISARM the motor.

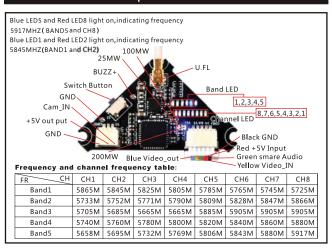


3.The default channel map for Larva X HD Frsky version is TAER1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch ,the Green LED on the flight controller will getting to be solid, this indicates the motor was armed . And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Larva X HD level before arming. Be careful and enjoy your flight now!





VTX Bands and Channels setup



VTX power set

Go to Betaflight configurator CLI tab,type"set vtx_power=1"to choose 25mw, "set vtx_power=2"to choose 100mw, "set vtx_power=3"to choose 200mw,need to type"save"

There are 3 ways to switch the vtx channels:

1. Short press the switch button to choose the VTX channel, Press and hold the butoon for 2 seconds and release to choose the VTX band(Can't save, it will lost the channel while power off)
2. If we need to use Channel 5705 then we should Go to Betaflight CLI, type the command:
Set VTX band=3

Set VTX_channel=1

save

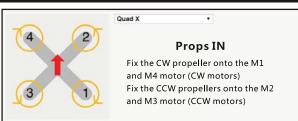
3.Enable Smaraudio for UART2, then move the stick of the transmitter (THR MID+YAW LEFT

+PITCH UP) to enter OSD Menu, Enter to Features, then enter to VTX SA to set VTX Band and channel



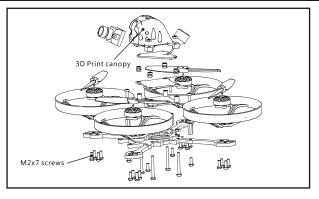


Mixer type and ESC/motor protocol





Whoop mode assemble



Default PID setting

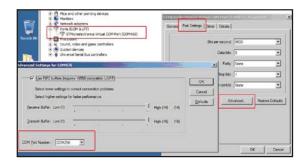
PID Settings			Filter Setting												
	Proportional		Integral		Derivative	Feedforward		RC Rate		Super Rate	Max Vel [deg/s]	RC Expo			
Basic/Acro														:0	
ROLL	42	:	60	:	40 ≎		70	:	1	1.00		0.70 \$	667	1	0.10 \$
PITCH:	46	:	70	:	38 ‡		75	:	J			0.70 \$	667	3	
	60		70		0 \$		0	:		1.00		0.70 ‡	667		0.00 \$

ESC Check and Flash firmware

- 1.Download New release Blhelisuite from:
- https://www.mediafire.com/folder/dx6kfaasyo24l/BLHeliSuite
- 2.Plug the usb and connect the flight controller to computer



3.Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step:



4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli_s firmware via the BLHEILISUITE, the firmware Target is "F-H-40"



Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

- $2. In stall STM BOOTLOAD \ Driver (STM \ Device in \ DFU \ MODE) \\ 3. Open \ Betaflight \ configurator \ and \ choose \ firmware \ target \ \ "Crazybee F4DX" \ , then select the$
- Open Betaflight configurator and choose firmware target "CrazybeeF4DX", then select the firmware version.
- $4. There \ are \ 2 \ ways \ to \ get \ in \ DFU \ Mode: 1). \ solder \ the \ boot \ pad \ and \ then \ plug \ USB \ to \ computer \ 2). \ loading \ betaflight \ firmware \ and \ hit \ "flash" \ , then \ it \ will \ getting \ into \ DFU \ Mode \ automatically.$
- $5. Open\, Zadig\, tools\, to\, replace\, the\, drivers\, from\, STM32\, Bootloader\, to\, WINUSB\, Driver.$
- 6. Reconnect the flight controller to the computer after replace driver done, and open Betaflight Configurator, loading firmware and flash.

